

Clip-OGD: An Experimental Design for Adaptive Neyman Allocation

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Jessica Dai
U.C. Berkeley

Algorithm Design for Causal Inference, INFORMS 2023

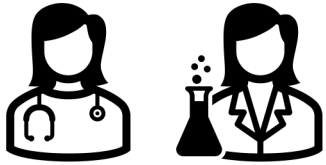


Chris Harshaw
MIT



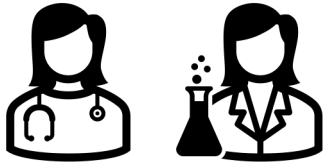
Paula Gradu
U.C. Berkeley

Randomized Experiments: Standard



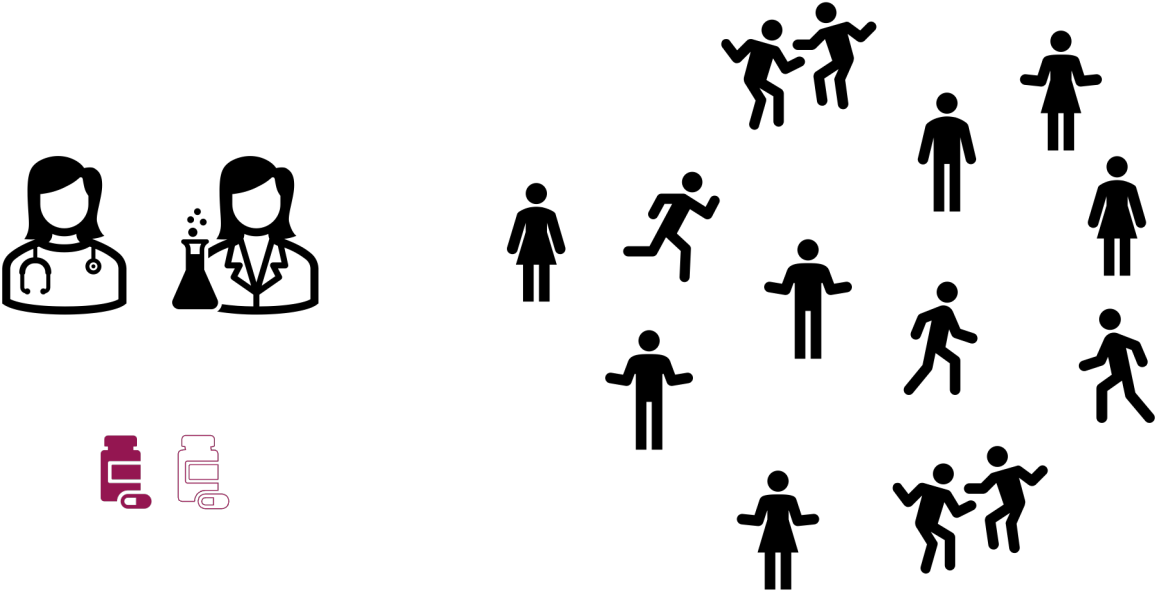
Experimenters

Randomized Experiments: Standard



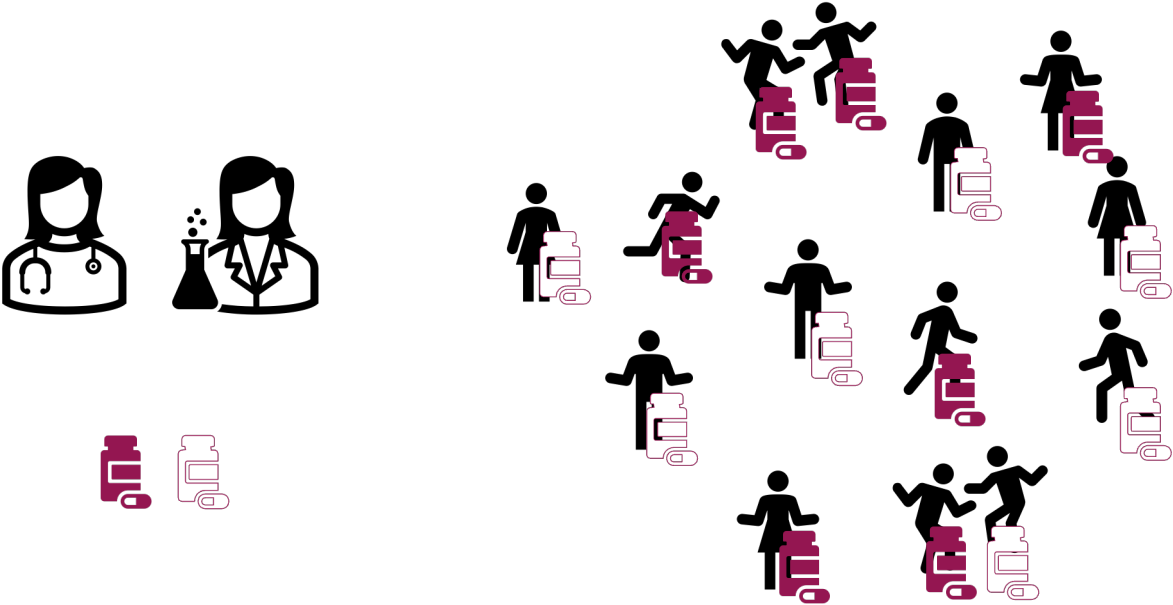
Treatment & control

Randomized Experiments: Standard



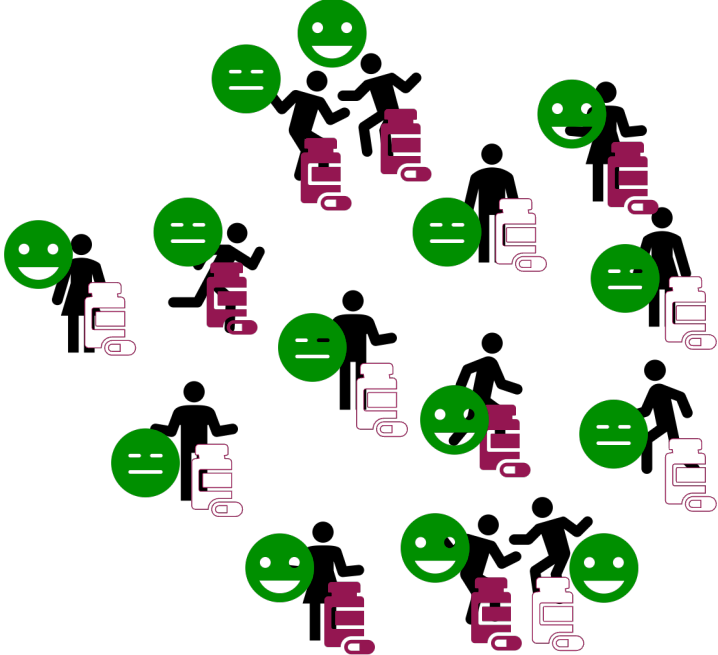
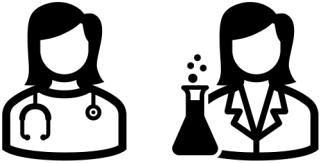
Experimental units

Randomized Experiments: Standard



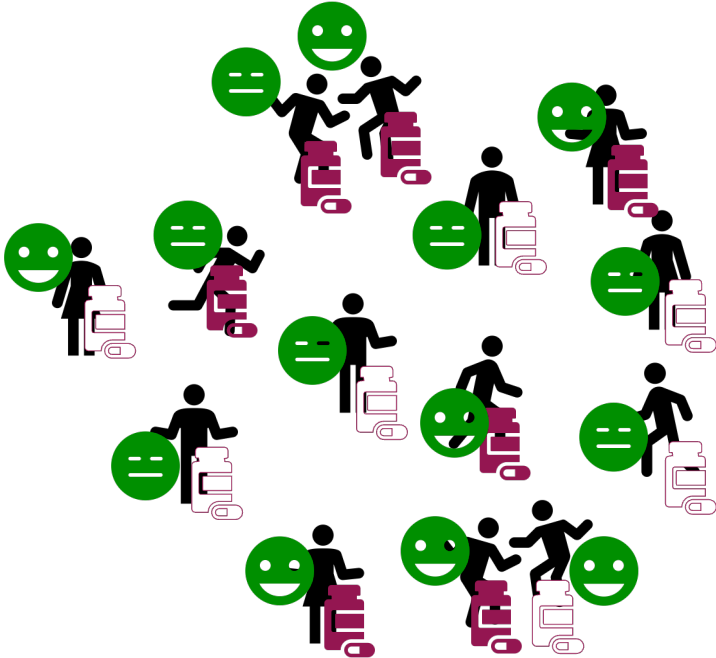
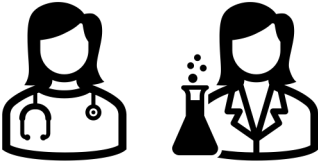
Treatment assignment

Randomized Experiments: Standard



Observe outcomes

Randomized Experiments: Standard

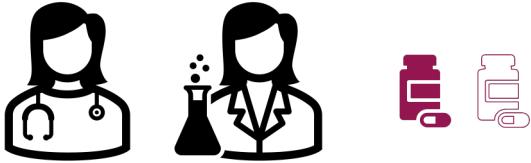


Randomized Experiments: Adaptive



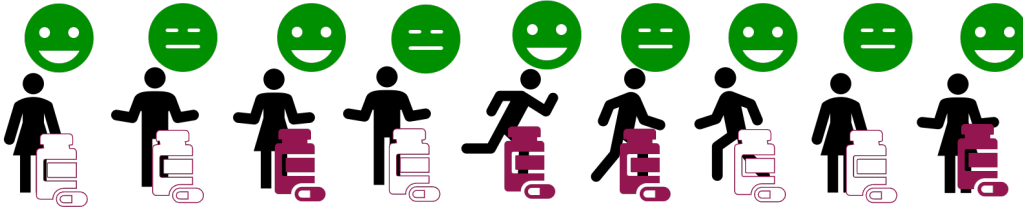
Experimenters and treatments, as before

Randomized Experiments: Adaptive



Sequential treatment assignments and outcome observations

Randomized Experiments: Adaptive



Randomized Experiments: Adaptive



Why would we want to do this?



Background: design-based causal inference

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We want to know the **average treatment effect**:

$$\tau = \frac{1}{T} \sum_{t \in [T]} y_t(1) - y_t(0)$$

Background: standard (non-adaptive) experiments

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How do we set p ?

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unbiased estimator

How do we set p ?

This work: minimize variance.

Neyman Variance: *the optimal allocation*

For any fixed p :

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$$T \cdot \text{Var}(\hat{\tau}) = S(1)^2 \left(\frac{1}{p} - 1 \right) + S(0)^2 \left(\frac{1}{1-p} - 1 \right) + 2\rho S(1)S(0)$$

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Second moment:

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***We don't know
these outcomes!***

and get variance*

**normalized*

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For any fixed ρ : $T \cdot \text{Var}(\hat{\tau}) = S(1)^2 \left(\frac{1}{n_1} - 1 \right) + S(0)^2 \left(\frac{1}{n_0} - 1 \right) + 2\rho S(1)S(0)$

***Can we get close
with adaptivity?***

Then, set

and get variance

$$T \cdot \text{Var}_N = 2(1 + \rho)S(1)S(0)$$

moment:

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similarity:

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Background: Prior work

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SOME ASPECTS OF THE SEQUENTIAL DESIGN OF EXPERIMENTS

HERBERT ROBBINS



Background: Prior work

Suppose we are dealing with two normally distributed populations with unknown means μ_1, μ_2 and variances σ_1^2, σ_2^2 , and that we wish to estimate the value of the difference $\mu_1 - \mu_2$. In order to concentrate on the point at issue we shall suppose that the total sample size, n , is fixed. There remains the question of how the n observations are to be divided between the two populations. If \bar{x}_1, \bar{x}_2 denote the means of samples of sizes n_1, n_2 from the two populations, then $\bar{x}_1 - \bar{x}_2$ is an unbiased estimator of $\mu_1 - \mu_2$, with variance $\sigma^2 = (\sigma_1^2/n_1) + (\sigma_2^2/n_2)$. For fixed $n = n_1 + n_2$, σ^2 is a minimum when $n_1/n_2 = \sigma_1/\sigma_2$.

... gestures at Neyman allocation

Some Aspects of the
Sequential Designs of
Experiments [Robbins 1952]



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Two-stage design: recently studied in Hahn et.al. 2011, Blackwell et.al. 2022

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Some Aspects of the
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Proposes a fully adaptive
experiment...

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How do we set P_t ?

$(1 - Z_t) \cdot y_t(0)$

2. Estimate

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Neyman Regret: *Neyman allocation as a benchmark*

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$$T \cdot \text{Var}(\hat{\tau}) = \frac{1}{T} \sum_{t \in [T]} \left(y_t(1)^2 \cdot \mathbb{E} \left[\frac{1}{P_t} \right] + y_t(0)^2 \cdot \mathbb{E} \left[\frac{1}{1 - P_t} \right] \right) - \frac{1}{T} \sum_{t \in [T]} (y_t(1) - y_t(0))^2$$

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Let's notate

$$f_t(p) = \frac{y_t(1)^2}{p} + \frac{y_t(0)^2}{1 - p}$$

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“controllable
contribution of
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Neyman Regret: *Neyman allocation as a benchmark*

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“controllable
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Then, Neyman Regret is defined as

$$\mathcal{R}_T = \sum_{t \in [T]} f_t(P_t) - \min_{p \in [0,1]} \sum_{t \in [T]} f_t(p)$$

Neyman Regret: *Neyman allocation as a benchmark*

$$\mathcal{R}_T = \sum_{t \in [T]} f_t(P_t) - \min_{p \in [0,1]} \sum_{t \in [T]} f_t(p)$$

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“incurred variance
from actual allocation”

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“incurred variance
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“minimum variance
from best possible
allocation”

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$$\mathcal{R}_T = \sum_{t \in [T]} f_t(P_t) - \min_{p \in [0,1]} \sum_{t \in [T]} f_t(p)$$

With this definition, minimizing Neyman regret also minimizes variance:

$$T \cdot V - T \cdot V_N = \frac{1}{T} \mathbb{E}[\mathcal{R}_T]$$

Neyman Regret: Neyman allocation as a benchmark

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With this definition, minimizing Neyman regret also minimizes variance:

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This turns a statistical problem into an algorithmic problem:

$$T \cdot V \rightarrow T \cdot V_N \iff \mathbb{E}[\mathcal{R}_T] = o(T)$$

Minimizing Neyman Regret

$$\mathcal{R}_T = \sum_{t \in [T]} f_t(P_t) - \min_{p \in [0,1]} \sum_{t \in [T]} f_t(p)$$

Minimizing Neyman Regret

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Good: objective $f_t(p) = \frac{y_t(1)^2}{p} + \frac{y_t(0)^2}{1-p}$ is convex

Minimizing Neyman Regret

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is convex

*can borrow
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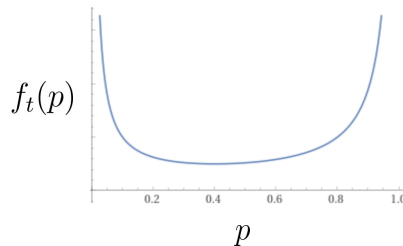
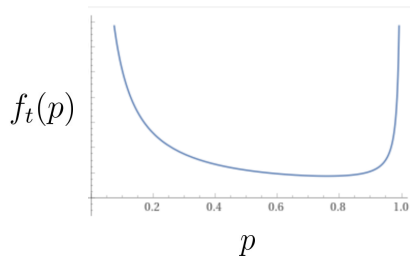
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Challenging: gradients $\nabla f_t(p)$ blow up at the boundary



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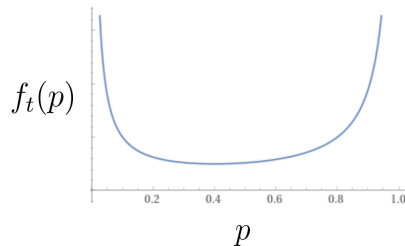
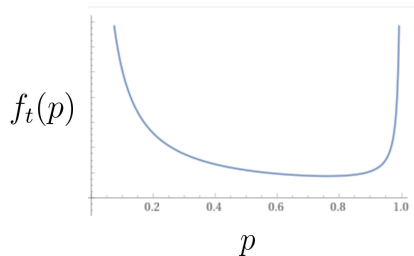
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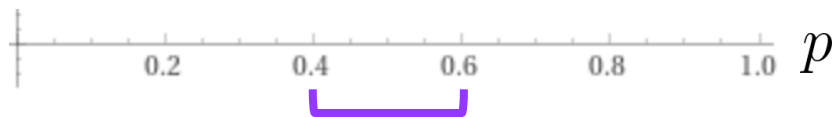
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need to clip gradient updates

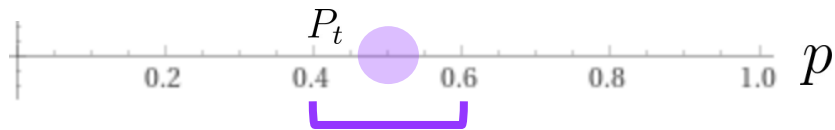


Our Algorithm: Clip-OGD (intuition)

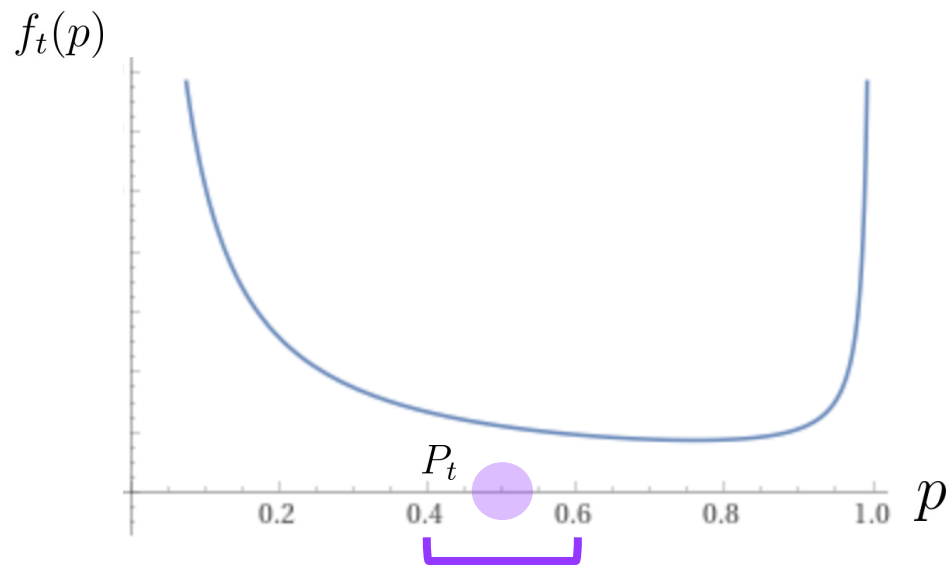
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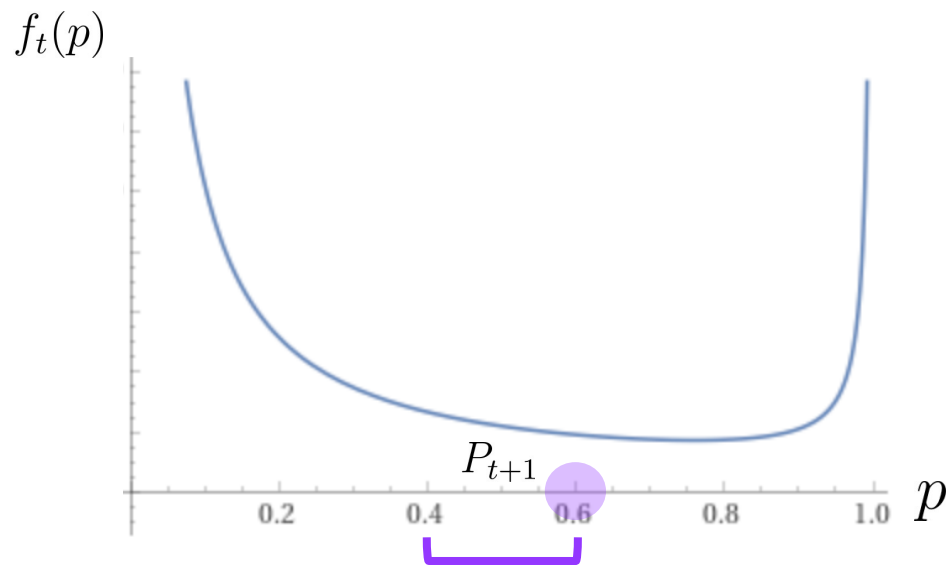
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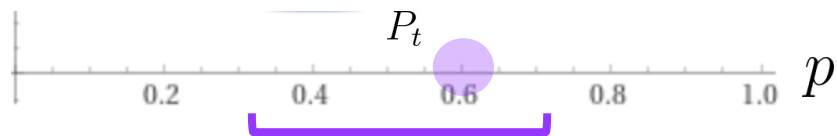


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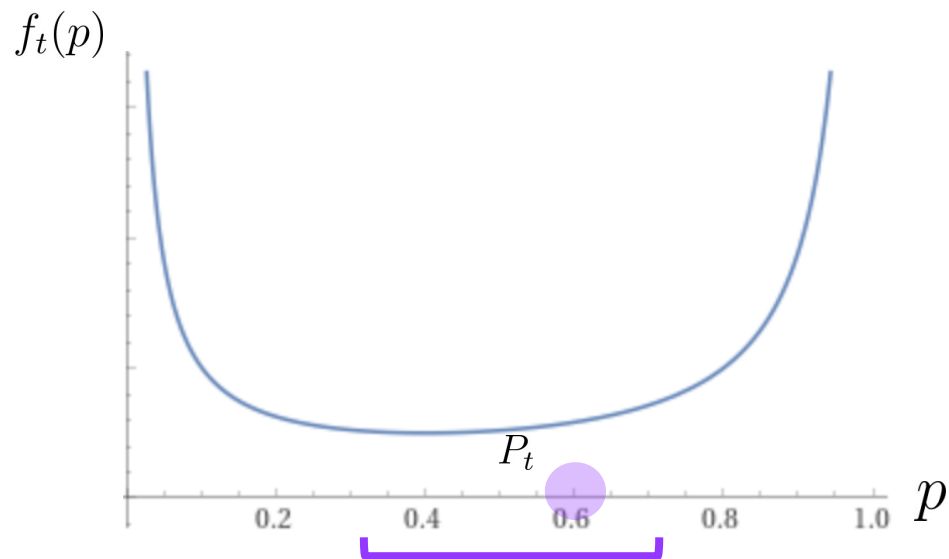


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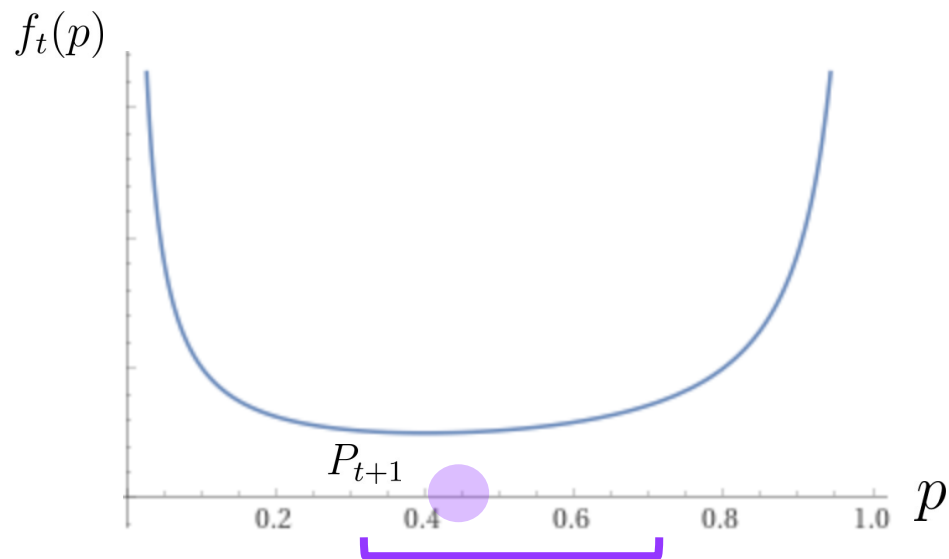
$$f_t(p)$$



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Input: Step size η and decay parameter α

Initialize $P_0 \leftarrow 1/2$ and $G_0 \leftarrow 0$

for $t = 1 \dots T$ **do**

 Set projection parameter $\delta_t = (1/2) \cdot t^{-1/\alpha}$

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G_t estimates the gradient of $f_t(P_t)$

Main Result: Neyman Regret of Clip-OGD

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Treatment: provide a new insurance product

Outcome: amount of money invested in equipment

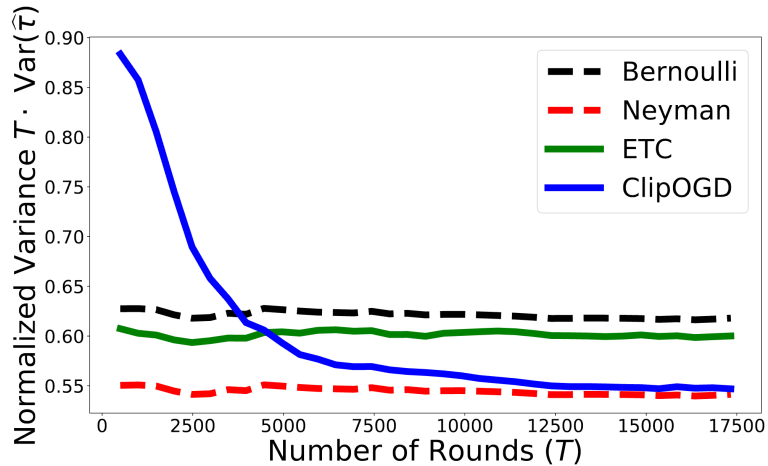
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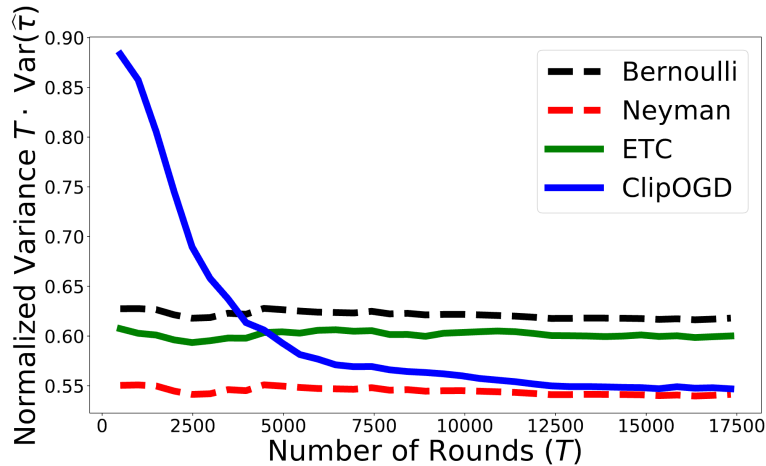


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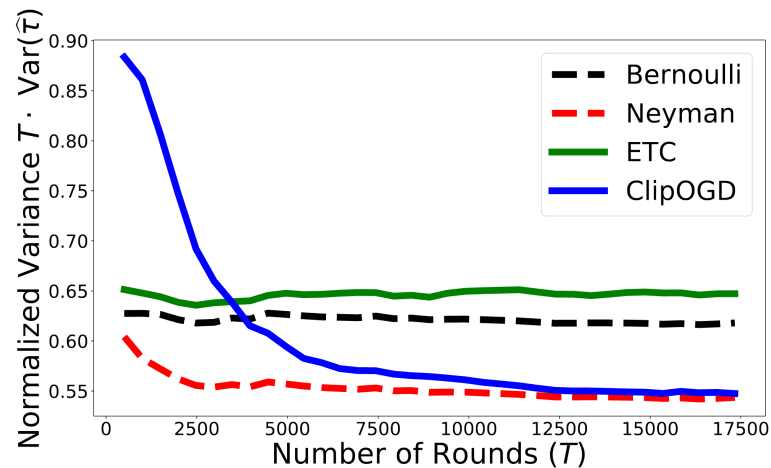
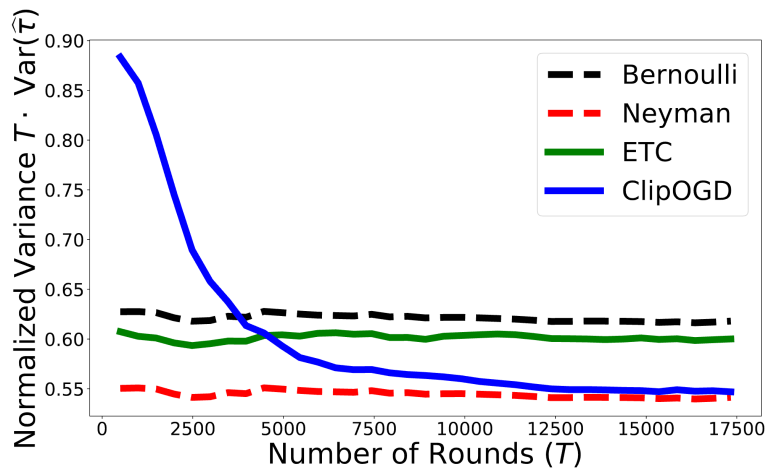
What if units came in a slightly different order?

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With first 100 outcomes corrupted

Additional Results: Other Designs?

$O(T)$ lower bound on explore-then-commit design

Impossibility result/ tradeoff for outcome and Neyman regret

Thank you!



Jessica Dai, UC Berkeley
jessicadai@berkeley.edu



Clip-OGD: An Experimental Design for Adaptive Neyman Allocation
Jessica Dai, Paula Gradu, Chris Harshaw
NeurIPS 2023
<https://arxiv.org/abs/2305.17187>



Chris Harshaw
MIT



Paula Gradu
U.C. Berkeley

Impossibility result: Neyman Regret and Outcome Regret

$$\text{Let } \mathcal{R}_T^{\text{outcome}} = \frac{1}{T} \sum_{t \in [T]} Y_t - \min_{i \in \{0,1\}} \sum_{t \in [T]} Y_t(i).$$

Suppose algorithm **A** for sequential allocation is no-outcome-regret:

$$\mathbb{E}[\mathcal{R}_T^{\text{outcome}}] = \mathcal{O}(T^q) \quad \text{for } q \in (0, 1)$$

Then **A** must suffer supralinear Neyman regret:

$$\mathbb{E}[\mathcal{R}_T^{\text{Neyman}}] \geq \Omega(T)$$

Any allocation which prioritizes outcomes **within the experiment** will worsen the **information gained from the experiment**.

Proof sketch:

definition of outcome regret implies

$$\sum_{t \in [T]} \mathbb{E}[P_t] \leq O(T^q)$$

which means that

$$\sum_{t \in [T]} \frac{1}{\mathbb{E}[P_t]} \geq O(T^{2-q})$$

which lower bounds

$$\mathbb{E} \left[\sum_{t \in [T]} f_t(P_t) \right] \geq O(T^{2-q})$$

and therefore the Neyman regret.